Binary Search Trees: Introduction

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Data Structures Data Structures and Algorithms

Learning Objectives

Provide examples of the sorts of problems we hope to solve with Binary Search Trees.
Show why data structures that we have

already covered are insufficient.

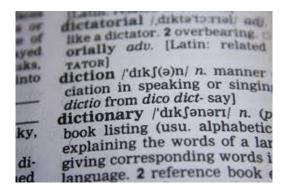


1 Local Search

2 Attempts

Dictionary Search

Find all words that start with some given string.



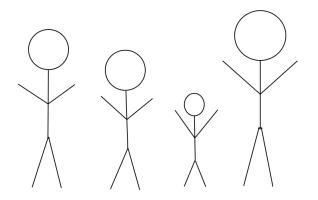
Date Ranges

Find all emails received in a given period.

Inbox					
FROM	KNOW	то	SUBJECT	SENT TIME •	
"lawiki.i2p admin" <j5uf></j5uf>		Bote User <uhod></uhod>	hi	Unknown	Î
anonymous		Bote User <uh0d></uh0d>	Sanders 2016	Aug 30, 2015 3:27 PM	Î
anonymous		Bote User <uh0d></uh0d>	I2PCon 2016	Aug 30, 2015 3:25 PM	Î
Anon Developer <gvbm></gvbm>		Bote User <uhod></uhod>	Re: Bote changess	Aug 30, 2015 2:54 PM	Î
I2P User <uuux></uuux>		Bote User <uhod></uhod>	Hello World!	Aug 30, 2015 2:51 PM	Î

Closest Height

Find the person in your class whose height is closest to yours.



Local Search

Definition

A Local Search Datastructure stores a number of elements each with a key coming from an ordered set. It supports operations:

- RangeSearch(x, y): Returns all elements with keys between x and y.
- NearestNeighbors(z): Returns the element with keys on either side of z.



1	4	6	7	10	13	15
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RangeSearch(5, 12)



RangeSearch(5, 12)

NearestNeighbors(3)

Dynamic Data Structure

We would also like to be able to modify the data structure as we go.

Insert(x): Adds a element with key x.
Delete(x): Removes the element with key x.



1	4	6	7	10	13	15
---	---	---	---	----	----	----



Insert(3)

1	3	4	6	7	10	13	15
---	---	---	---	---	----	----	----



Insert(3)

Delete(10)

1	3	4	6	7	13	15
---	---	---	---	---	----	----

Problem

If an empty data structure is given these commands what does it output at the end?

- Insert(3)
- Insert(8)
- Insert(5)
- Insert(10)
- Delete(8)
- Insert(12)
- NearestNeighbors(7)





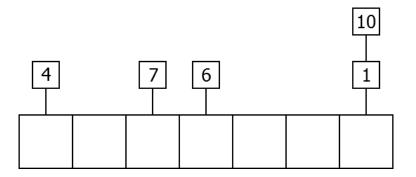


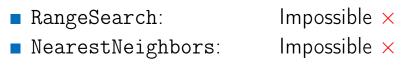
1 Local Search

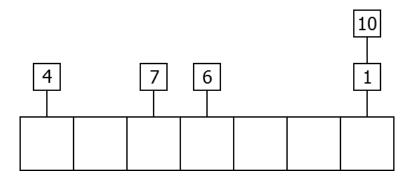


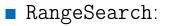


Impossible ×



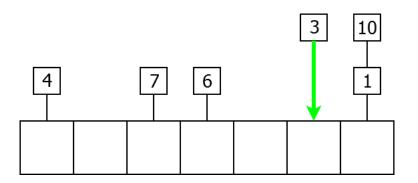






- NearestNeighbors:
- Insert:

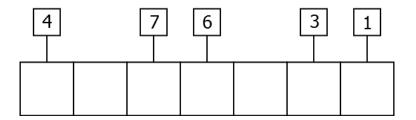
Impossible \times Impossible \times $O(1) \checkmark$



- RangeSearch:
- NearestNeighbors:
- Insert:
- Delete:

Impossible × Impossible × $O(1) \checkmark$ $O(1) \checkmark$











7 1	10 4	13	1	6	15
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Array

- RangeSearch:
- NearestNeighbors:

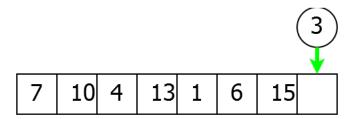


7	10	4	13	1	6	15
---	----	---	----	---	---	----

Array

- RangeSearch:
- NearestNeighbors:
- Insert:

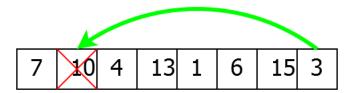
 $O(n) \times O(n) \times O(1) \checkmark$



Array

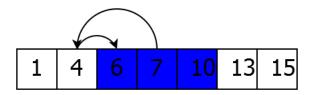
- RangeSearch:
- NearestNeighbors:
- Insert:
- Delete:

 $O(n) \times O(n) \times O(1) \checkmark O(1) \checkmark$



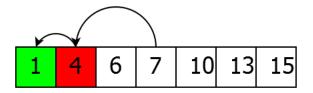


 $O(\log(n))$



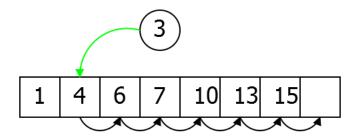
- RangeSearch:
- NearestNeighbors:

 $O(\log(n)) \checkmark$ $O(\log(n)) \checkmark$



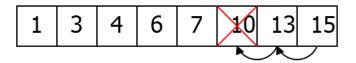
- RangeSearch:
- NearestNeighbors:
- Insert:

 $O(\log(n)) \checkmark O(\log(n)) \checkmark O(n) \times O$



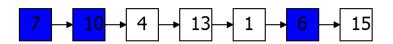
- RangeSearch:
- NearestNeighbors:
- Insert:
- Delete:

 $O(\log(n)) \checkmark O(\log(n)) \checkmark O(n) \times O$





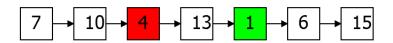




RangeSearch:

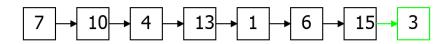
NearestNeighbors:





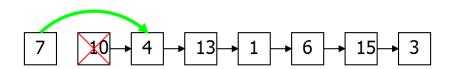
- RangeSearch:
- NearestNeighbors:
- Insert:

 $O(n) \times O(n) \times O(1) \checkmark$



- RangeSearch:
- NearestNeighbors:
- Insert:
- Delete:

 $O(n) \times O(n) \times O(1) \checkmark O(1) \checkmark$



Need Something New

Problem

Previous data structures won't work. We need something new.